# Hw #8 The linear response representation

### Changjian Xie

### June 9, 2018

## 1 Spin Waves in Ferromagnets

### 1.1 Motion of spin waves in ferromagnets

Considering the propogations of spin waves in a uniaxial ferromagnet and assuming that

$$\overrightarrow{\mathcal{M}}(r,t) = \overrightarrow{\mathcal{M}}_0(r,t) + \overrightarrow{\boldsymbol{m}}(r,t) \tag{1}$$

$$\vec{H}^{(i)}(r,t) = \vec{H}_0^{(i)} + \vec{h}(r,t), \qquad (2)$$

where  $\overrightarrow{m}$  and  $\overrightarrow{h}$  are small pertubations from the equilibrium magnetization  $\overrightarrow{\mathcal{M}}_0$ and internal field  $\overrightarrow{H}_0^{(i)}$ . The expression of effective field to eq. (1) and eq. (2) is given as

$$\mathcal{H} = \overrightarrow{\mathbf{h}} + \alpha_{ij} \frac{\partial^2 \overrightarrow{\mathbf{m}}}{\partial x_i \partial x_j} - \frac{1}{\overrightarrow{\mathcal{M}}_0^2} \{ \overrightarrow{\mathcal{M}}_0 \cdot \overrightarrow{H}_0^{(i)} + \beta (\overrightarrow{\mathcal{M}}_0 \cdot \overrightarrow{\mathbf{n}})^2 \} \overrightarrow{\mathbf{m}} + \beta \overrightarrow{\mathbf{n}} (\overrightarrow{\mathbf{m}} \cdot \overrightarrow{\mathbf{n}}) - 4 \overrightarrow{\mathcal{M}}_0 f'' (\overrightarrow{\mathcal{M}}_0^2) (\overrightarrow{\mathcal{M}}_0 \cdot \overrightarrow{\mathbf{m}}). \tag{3}$$

The linearized equation of motion will be of the form

$$\frac{\partial \vec{m}}{\partial t} = g[\vec{\mathcal{M}}_0, \vec{H}]. \tag{4}$$

Note that  $\overrightarrow{\mathcal{M}}_0 \times \overrightarrow{\mathcal{M}}_0 = 0$  and then get

Using the Fourier repersentations

$$\vec{\boldsymbol{m}}(\vec{\boldsymbol{r}},t) = \int \vec{\boldsymbol{m}}(\vec{\boldsymbol{k}},\omega) e^{i(\vec{\boldsymbol{k}}\cdot\vec{\boldsymbol{r}}-\omega t)} d\vec{\boldsymbol{k}} d\omega, \qquad (6)$$

$$\vec{h}(\vec{r},t) = \int \vec{h}(\vec{k},\omega) e^{i(\vec{k}\cdot\vec{r}-\omega t)} d\vec{k} d\omega.$$
(7)

We have from eq. (5) that

$$-i\omega \overrightarrow{\boldsymbol{m}}(\overrightarrow{\boldsymbol{k}},\omega) = g\left[\overrightarrow{\mathcal{M}}_{0}, \overrightarrow{\boldsymbol{h}}(\overrightarrow{\boldsymbol{k}},\omega) - \left\{\alpha_{ij}k_{i}k_{j} + \frac{\overrightarrow{\mathcal{M}}_{0}\cdot\overrightarrow{H}_{0}^{(i)}}{\overrightarrow{\mathcal{M}}_{0}^{2}} + \beta \frac{(\overrightarrow{\mathcal{M}}_{0}\cdot\overrightarrow{\boldsymbol{n}})^{2}}{\overrightarrow{\mathcal{M}}_{0}^{2}}\right\} \overrightarrow{\boldsymbol{m}}(\overrightarrow{\boldsymbol{k}},\omega)$$

$$+ \beta \overrightarrow{\boldsymbol{n}}(\overrightarrow{\boldsymbol{n}}\cdot\overrightarrow{\boldsymbol{m}}(\overrightarrow{\boldsymbol{k}},\omega))\right].$$
(8)

For simplicity, the z-axis lies along  $\overrightarrow{\mathcal{M}}_0$  and the x-axis lies in the plane containing the anisotropy axis  $\overrightarrow{n}$  and  $\overrightarrow{\mathcal{M}}_0$ . Let  $\psi$  the angle between the vector  $\overrightarrow{n}$  and  $\overrightarrow{\mathcal{M}}_0$ . Thus, we let  $\overrightarrow{\mathcal{M}}_0 = (0, 0, \mathcal{M}_0)^T$  and  $\overrightarrow{n} = (\sin \psi, 0, \cos \psi)^T$ , where  $(\cdot)^T$  denotes the transpose of the given vector. We then get

$$(\vec{\boldsymbol{m}}\cdot\vec{\boldsymbol{n}})\vec{\boldsymbol{n}} = A\vec{\boldsymbol{m}}, \quad \vec{\mathcal{M}}_0\cdot\vec{\boldsymbol{n}} = \mathcal{M}_0\cos\psi,$$
(9)

where the matrix is given by

$$A = \begin{bmatrix} \sin^2 \psi & 0 & \cos \psi \sin \psi \\ 0 & 0 & 0 \\ \cos \psi \sin \psi & 0 & \cos^2 \psi \end{bmatrix}.$$
 (10)

Note, however, that

$$\overrightarrow{\mathcal{M}}_0 \times \overrightarrow{\boldsymbol{h}} = B \overrightarrow{\boldsymbol{h}},\tag{11}$$

where the matrix B is

$$B = \begin{bmatrix} 0 & -\mathcal{M}_0 & 0\\ \mathcal{M}_0 & 0 & 0\\ 0 & 0 & 0 \end{bmatrix}.$$
 (12)

Thus, we have from eq. (8) that

$$\left(g\left\{\alpha_{ij}k_ik_j + \frac{\overrightarrow{\mathcal{M}}_0 \cdot \overrightarrow{H}_0^{(i)}}{\overrightarrow{\mathcal{M}}_0^2} + \beta \cos^2\psi\right\}B - i\omega I - g\beta BA\right)\overrightarrow{\mathbf{m}} = gB\overrightarrow{\mathbf{h}}.$$
 (13)

where I is the identity matrix. We then from eq. (13) that

$$\overrightarrow{\boldsymbol{m}} = \chi \overrightarrow{\boldsymbol{h}}, \qquad (14)$$

with the susceptibility matrix

$$\chi = \left[gpB - i\omega I - g\beta BA\right]^{-1}gB.$$
(15)

where  $p = \alpha_{ij}k_ik_j + \frac{\overrightarrow{\mathcal{M}}_0 \cdot \overrightarrow{\mathcal{H}}_0^{(i)}}{\overrightarrow{\mathcal{M}}_0^2} + \beta \cos^2 \psi$ . If we denote  $C = gpB - i\omega I - g\beta BA$ and then get

$$C^{-1} = \frac{C^*}{\det(C)},$$
 (16)

where  $C^*$  is the adjoint matrix of C and  $\det(C)$  denotes the determinant of the matrix C. Here,

$$C = \begin{bmatrix} -i\omega & -g\mathcal{M}_0p & 0\\ g\mathcal{M}_0p - g\beta\mathcal{M}_0\sin^2\psi & -i\omega & -g\beta\mathcal{M}_0\cos\psi\sin\psi\\ 0 & 0 & -i\omega \end{bmatrix}, \quad (17)$$

and

$$C^* = \begin{bmatrix} -\omega^2 & -i\omega g \mathcal{M}_0 p & g \mathcal{M}_0 p(g\beta \mathcal{M}_0 \cos \psi \sin \psi) \\ i\omega(g \mathcal{M}_0 p - g\beta \mathcal{M}_0 \sin^2 \psi) & -\omega^2 & -i\omega g\beta \mathcal{M}_0 \cos \psi \sin \psi \\ 0 & 0 & -\omega^2 + g \mathcal{M}_0 p(g \mathcal{M}_0 p - g\beta \mathcal{M}_0 \sin^2 \psi) \end{bmatrix}.$$
(18)

Thus, we have from eq. (17) that

$$\det(C) = -i\omega[-\omega^2 + g\mathcal{M}_0 p(g\mathcal{M}_0 p - g\beta\mathcal{M}_0 \sin^2\psi)].$$
 (19)

It follows from eq. (15) and eq. (16) yields that

$$\chi = \frac{g}{\det(C)} C^* B$$
(20)  
=:  $\frac{g}{\det(C)} D$ ,

where

$$D = \begin{bmatrix} -i\omega g \mathcal{M}_0^2 p & \mathcal{M}_0 \omega^2 & 0\\ -\mathcal{M}_0 \omega^2 & -\mathcal{M}_0 i \omega (g \mathcal{M}_0 p - g \mathcal{M}_0 \sin^2 \psi) & 0\\ 0 & 0 & 0 \end{bmatrix}.$$
 (21)

If we introduce the notations by

$$\Omega_1 = g\mathcal{M}_0 p = g\mathcal{M}_0(\alpha_{ij}k_ik_j + \frac{\overrightarrow{\mathcal{M}}_0 \cdot \overrightarrow{H}_0^{(i)}}{\overrightarrow{\mathcal{M}}_0^2} + \beta \cos^2 \psi)$$
(22)

$$\Omega_2 = g\mathcal{M}_0 p - g\beta\mathcal{M}_0 \sin^2 \psi = g\mathcal{M}_0(\alpha_{ij}k_ik_j + \frac{\overline{\mathcal{M}}_0 \cdot \overline{H}_0^{(i)}}{\overline{\mathcal{M}}_0^2} + \beta\cos 2\psi).$$

We then derive that

$$\chi = \begin{bmatrix} \chi_{xx} & \chi_{xy} & 0\\ \chi_{yx} & \chi_{yy} & 0\\ 0 & 0 & 0 \end{bmatrix},$$
 (23)

where

$$\chi_{xx} = \frac{g\mathcal{M}_0\Omega_1}{\Omega_1\Omega_2 - \omega^2}$$

$$\chi_{yy} = \frac{g\mathcal{M}_0\Omega_2}{\Omega_1\Omega_2 - \omega^2}$$

$$\chi_{xy} = -\chi_{yx} = \frac{i\omega g\mathcal{M}_0}{\Omega_1\Omega_2 - \omega^2}.$$
(24)

### 1.2 Damping of spin waves

The equation of motion for  $\overrightarrow{\mathcal{M}}$  will be the form

$$\frac{\partial \overrightarrow{\mathcal{M}}}{\partial t} = g[\overrightarrow{\mathcal{M}}, \mathcal{H}] + \frac{1}{\tau_2} \mathcal{H} - \frac{1}{\tau_1} [\overrightarrow{\boldsymbol{n}}, [\overrightarrow{\boldsymbol{n}}, \mathcal{H}]], \qquad (25)$$

where  $\overrightarrow{n} = \frac{\mathcal{M}_0}{|\mathcal{M}_0|}$  and  $\tau_1, \tau_2$  are constants which have the dimensions of time,  $\tau_2 > 0, \frac{1}{\tau_1} + \frac{1}{\tau_2} > 0$ . Here, we consider the uniaxial ferromagnetic and assume that the field  $\overrightarrow{H}_0^{(i)}$  is parallel to the easy axis. The effective magnetic field is

$$\mathcal{H} = \overrightarrow{\boldsymbol{h}} - \left(\beta + \frac{\overrightarrow{H}_{0}^{(i)}}{\mathcal{M}_{0}}\right) \overrightarrow{\boldsymbol{m}} + \alpha_{ij} \frac{\partial^{2} \overrightarrow{\boldsymbol{m}}}{\partial x_{i} \partial x_{j}} + \left[\beta - 4\mathcal{M}_{0}^{2} f''(\mathcal{M}_{0}^{2})\right] (\overrightarrow{\boldsymbol{m}} \cdot \overrightarrow{\boldsymbol{n}}) \overrightarrow{\boldsymbol{n}}.$$
 (26)

Note, however, that the quantity  $f''(\mathcal{M}_0^2)$  in this expression for  $\mathcal{H}$  can be readily be related to the static susceptibility of the ferromagnetic, that is

$$\chi^0_{zz} = \frac{\partial \mathcal{M}_0}{\partial H_0^{(i)}}.$$
(27)

We have seen that in the state of equilibrium

$$H_0^{(i)} + \beta \mathcal{M}_0 - 2\mathcal{M}_0 f'(\mathcal{M}_0^2).$$
(28)

We have from eq. (28) that

$$\beta = 2f'(\mathcal{M}_0^2) - \frac{H_0^{(i)}}{\mathcal{M}_0}.$$
(29)

We take derivative for  $\mathcal{M}_0$  regarding  $H_0$  and get

$$4\mathcal{M}_0^2 f''(\mathcal{M}_0^2) = \frac{1}{\chi_{zz}^0} - \frac{H_0^{(i)}}{\mathcal{M}_0}$$
(30)

The linearized equation of motion is

$$\frac{\partial \vec{\boldsymbol{m}}}{\partial t} = g[\vec{\mathcal{M}}_0, \mathcal{H}] + \frac{1}{\tau_2} \mathcal{H} - \frac{1}{\tau_1} [\vec{\boldsymbol{n}}, [\vec{\boldsymbol{n}}, \mathcal{H}]].$$
(31)

Using the Fourier transform eq. (6), then we get

$$-i\omega \overrightarrow{\boldsymbol{m}}(\overrightarrow{\boldsymbol{k}},\omega) = g \left[ \overrightarrow{\mathcal{M}}_{0}, \overrightarrow{\boldsymbol{h}} - \left(\beta + \frac{H_{0}^{(i)}}{\mathcal{M}_{0}}\right) \overrightarrow{\boldsymbol{m}} - \alpha_{ij} k_{i} k_{j} \overrightarrow{\boldsymbol{m}} + \beta (\overrightarrow{\boldsymbol{m}} \cdot \overrightarrow{\boldsymbol{n}}) \overrightarrow{\boldsymbol{n}} \right]$$
(32)

$$+\frac{1}{\tau_{2}}\left\{\overrightarrow{\vec{h}}-\left(\beta+\frac{H_{0}^{(i)}}{\mathcal{M}_{0}}\right)\overrightarrow{\vec{m}}-\alpha_{ij}k_{i}k_{j}\overrightarrow{\vec{m}}+\left(\beta-4\mathcal{M}_{0}^{2}f''(\mathcal{M}_{0}^{2})\right)\left(\overrightarrow{\vec{m}}\cdot\overrightarrow{\vec{n}}\right)\overrightarrow{\vec{n}}\right\}\\-\frac{1}{\tau_{1}}\left[\overrightarrow{\vec{n}},\left[\overrightarrow{\vec{n}},\overrightarrow{\vec{h}}-\left(\beta+\frac{H_{0}^{(i)}}{\mathcal{M}_{0}}\right)\overrightarrow{\vec{m}}-\alpha_{ij}k_{i}k_{j}\overrightarrow{\vec{m}}+\left(\beta-4\mathcal{M}_{0}^{2}f''(\mathcal{M}_{0}^{2})\right)\left(\overrightarrow{\vec{m}}\cdot\overrightarrow{\vec{n}}\right)\overrightarrow{\vec{n}}\right]\right].$$

Rewrite the above representation in matrix form as

$$\begin{bmatrix} g(\beta + \frac{H_0^{(i)}}{\mathcal{M}_0} + \alpha_{ij}k_ik_j)B - g\beta BA - i\omega I + \frac{1}{\tau_2} \left(\beta + \frac{H_0^{(i)}}{\mathcal{M}_0} + \alpha_{ij}k_ik_j\right)I & (33) \\ - \frac{1}{\tau_2} \left(\beta + \frac{H_0^{(i)}}{\mathcal{M}_0} - \frac{1}{\chi_{zz}^0}\right)A + \frac{1}{\tau_1} \left[\beta + \frac{H_0^{(i)}}{\mathcal{M}_0} - \alpha_{ij}k_ik_j\right]F \end{bmatrix} \overrightarrow{\boldsymbol{m}}$$

$$= (gB + \frac{1}{\tau_2}I - \frac{1}{\tau_1}F)\overrightarrow{\boldsymbol{h}}.$$

$$(34)$$

Here, the matrix  $\boldsymbol{I}$  is the identity matrix, and We then derive that

$$A = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}, B = \begin{bmatrix} 0 & -\mathcal{M}_0 & 0 \\ \mathcal{M}_0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}, F = \begin{bmatrix} -1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}.$$
 (35)

Thus, BA is the full-zero matrix. We introduce the notation

$$G = g(\beta + \frac{H_0^{(i)}}{\mathcal{M}_0} + \alpha_{ij}k_ik_j)B - g\beta BA - i\omega I + \frac{1}{\tau_2} \left(\beta + \frac{H_0^{(i)}}{\mathcal{M}_0} + \alpha_{ij}k_ik_j\right)I \quad (36)$$
$$- \frac{1}{\tau_2} \left(\beta + \frac{H_0^{(i)}}{\mathcal{M}_0} - \frac{1}{\chi_{zz}^0}\right)A + \frac{1}{\tau_1} \left[\beta + \frac{H_0^{(i)}}{\mathcal{M}_0} - \alpha_{ij}k_ik_j\right]F,$$

and

$$J = gB + \frac{1}{\tau_2}I - \frac{1}{\tau_1}F.$$
 (37)

We then obtain

$$\overrightarrow{\boldsymbol{m}} = \chi \overrightarrow{\boldsymbol{h}},\tag{38}$$

where

$$\chi = G^{-1}J = \frac{G^*}{\det(G)}J.$$
(39)

After calculation, we get

$$G = \begin{bmatrix} G_{11} & G_{12} & 0\\ G_{21} & G_{22} & 0\\ 0 & 0 & G_{33} \end{bmatrix}, J = \begin{bmatrix} J_{11} & J_{12} & 0\\ J_{21} & J_{22} & 0\\ 0 & 0 & J_{33} \end{bmatrix},$$
(40)

where

$$\begin{split} G_{11} &= -i\omega + \frac{1}{\tau_2} \Big(\beta + \frac{H_0^{(i)}}{\mathcal{M}_0} + \alpha_{ij}k_ik_j\Big) - \frac{1}{\tau_1} \Big(\beta + \frac{H_0^{(i)}}{\mathcal{M}_0} - \alpha_{ij}k_ik_j\Big) \\ G_{12} &= -g\mathcal{M}_0 \Big(\beta + \frac{H_0^{(i)}}{\mathcal{M}_0} + \alpha_{ij}k_ik_j\Big), \quad G_{13} = 0 \\ G_{21} &= g\mathcal{M}_0 \Big(\beta + \frac{H_0^{(i)}}{\mathcal{M}_0} + \alpha_{ij}k_ik_j\Big) \\ G_{22} &= -i\omega + \frac{1}{\tau_2} \Big(\beta + \frac{H_0^{(i)}}{\mathcal{M}_0} + \alpha_{ij}k_ik_j\Big) + \frac{1}{\tau_1} \Big(\beta + \frac{H_0^{(i)}}{\mathcal{M}_0} - \alpha_{ij}k_ik_j\Big) \\ G_{23} &= 0 \quad G_{31} = 0 \quad G_{32} = 0 \\ G_{33} &= -i\omega + \frac{1}{\tau_2} \Big(\alpha_{ij}k_ik_j + \frac{1}{\chi_{zz}^0}\Big), \end{split}$$

 $\quad \text{and} \quad$ 

$$J_{11} = \frac{1}{\tau_1} + \frac{1}{\tau_2} \quad J_{12} = -g\mathcal{M}_0 \quad J_{13} = 0$$
$$J_{21} = g\mathcal{M}_0 \quad J_{22} = \frac{1}{\tau_2} - \frac{1}{\tau_1} \quad J_{23} = 0$$
$$J_{31} = 0 \quad J_{32} = 0 \quad J_{33} = \frac{1}{\tau_2},$$

and

$$G^* = \begin{bmatrix} G_{22}G_{33} & -G_{12}G_{33} & 0\\ -G_{21}G_{33} & G_{11}G_{33} & 0\\ 0 & 0 & G_{11}G_{22} - G_{12}G_{21} \end{bmatrix}.$$
 (41)

We then derive the following expression for the high-frequency susceptibility tensor:

$$\chi = \begin{bmatrix} \chi_{xx} & \chi_{xy} & 0\\ \chi_{yx} & \chi_{yy} & 0\\ 0 & 0 & \chi_{zz} \end{bmatrix},$$
(42)

in which

$$\chi_{xx} = \left[ G_{22}G_{33} \left( \frac{1}{\tau_1} + \frac{1}{\tau_2} \right) - g\mathcal{M}_0 G_{12}G_{33} \right] / \det(G)$$
  

$$\chi_{xy} = \left[ -G_{22}G_{33}g\mathcal{M}_0 - G_{12}G_{33} \left( \frac{1}{\tau_2} - \frac{1}{\tau_1} \right) \right] / \det(G)$$
  

$$\chi_{yx} = \left[ -G_{21}G_{33} \left( \frac{1}{\tau_1} + \frac{1}{\tau_2} \right) + G_{11}G_{33}g\mathcal{M}_0 \right] / \det(G)$$
  

$$\chi_{yy} = \left[ G_{21}G_{33}g\mathcal{M}_0 + G_{11}G_{33} \left( \frac{1}{\tau_2} - \frac{1}{\tau_1} \right) \right] / \det(G)$$
  

$$\chi_{zz} = \left[ (G_{11}G_{22} - G_{12}G_{21}) \frac{1}{\tau_2} \right] / \det(G),$$

6

where  $det(G) = G_{33}[G_{11}G_{22} - G_{12}G_{21}]$ . We finally get the expression of the susceptibility tensor in which the entries as

$$\chi_{xx} = \chi_{yy} = \frac{g\mathcal{M}_0\Omega - (i\omega/\tau) + (\Omega/g\mathcal{M}_0\tau^2)}{\Omega^2 - (\omega + i\Omega/g\mathcal{M}_0\tau)^2}$$
$$\chi_{zz} = \frac{\chi_{zz}^0}{1 + \chi_{zz}^0(\alpha_{ij}k_ik_j - i\omega\tau_2)},$$
$$\chi_{xy} = -\chi_{yx} = \frac{i\omega g\mathcal{M}_0}{\Omega^2 - (\omega + i\Omega/g\mathcal{M}_0\tau)^2},$$

where

$$\frac{1}{\tau} = \frac{1}{\tau_1} + \frac{1}{\tau_2}, \quad \Omega = g\mathcal{M}_0 \big(\alpha_{ij}k_ik_j + \frac{H_0^{(i)}}{\mathcal{M}_0} + \beta\big).$$